# NONEXISTENCE OF MULTI-BUBBLE SOLUTIONS <br> FOR A HIGHER ORDER MEAN FIELD EQUATION ON CONVEX DOMAINS 

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#### Abstract

In this note, we show that there does not exist any blowingup solution sequence with multiple blow up points to a $2 p$-th order mean field equation $$
\begin{cases}(-\Delta)^{p} u=\rho \frac{V(x) e^{u}}{\int_{\Omega} V(x) e^{u} d x} & \text { in } \Omega \subset \mathbb{R}^{2 p} \\ (-\Delta)^{j} u=0 \quad \text { on } \partial \Omega, & (j=0,1, \cdots p-1)\end{cases}
$$ for $p \in \mathbb{N}$, if a bounded smooth domain $\Omega$ is convex and the function $V$ satisfies some conditions.


Keywords: blowing-up solution, higher-order mean field equation, Green's function.

2010 Mathematics Subject Classifications: 35J35, 35J40.

## 1. Introduction

Recently, many authors have been interested in the study of nonlinear elliptic partial differential equations involving the higher-order differential operator, because of its connection to the conformal geometry. One of the most important conformally invariant differential operators on a four-dimensional Riemannian manifold $(M, g)$ is a Paneitz operator, defined as

$$
P_{g}=\Delta_{g}^{2}-\delta_{g}\left(\frac{2}{3} S_{g}-2 R i c_{g}\right) d
$$

where $\Delta_{g}$ denotes the Laplace-Beltrami operator with respect to $g$, $\delta_{g}$ the co-differential, $d$ the exterior differential, $S_{g}$ and $R i c_{g}$ denote the scalar and Ricci curvature of the metric $g$. By this symbol, the equation of prescribing $Q$-curvature on $(M, g)$ is described as

$$
P_{g} u+2 Q_{g}=2 \bar{Q}_{g_{u}} e^{4 u}
$$

where $Q_{g}$ is the $Q$-curvature of the original metric $g, \bar{Q}_{g_{u}}$ is the $Q$ curvature of the new metric $g_{u}=e^{4 u} g$. If $(M, g)$ is $\mathbb{R}^{4}$ with its standard euclidean metric, the Paneitz operator $P_{g}$ is nothing but $\Delta^{2}=\Delta \Delta$ where $\Delta=\sum_{i=1}^{4} \frac{\partial^{2}}{\partial x_{i}^{2}}$ is the Laplacian in $\mathbb{R}^{4}$, and the equation of prescribing $Q$-curvature becomes of the form

$$
\Delta^{2} u=\rho \frac{V(x) e^{4 u}}{\int_{\Omega} V(x) e^{4 u} d x}
$$

See for example, [7], [10], [8] and the references therein.
In this paper, we consider a generalization of it, namely, we concern the following $2 p$-th order mean field equation $(p \in \mathbb{N})$

$$
\begin{cases}(-\Delta)^{p} u=\rho \frac{V(x) e^{u}}{\int_{\Omega} V(x) e^{u} d x} & \text { in } \Omega \subset \mathbb{R}^{2 p},  \tag{1.1}\\ (-\Delta)^{j} u=0 \quad \text { on } \partial \Omega, & (j=0,1, \cdots p-1),\end{cases}
$$

where $\Omega$ is a smooth bounded domain in $\mathbb{R}^{2 p}, \rho$ is a positive parameter and $V \in C^{2, \beta}(\Omega)$ is a positive function. Let us define the variational functional $I_{\rho}: X \rightarrow \mathbb{R}$,

$$
I_{\rho}(u)=\frac{1}{2} \int_{\Omega}\left|(-\Delta)^{\frac{p}{2}} u\right|^{2} d x-\rho \log \int_{\Omega} V(x) e^{u} d x
$$

where

$$
X=H^{p}(\Omega) \cap\left\{u \mid(-\Delta)^{j} u \in H_{0}^{1}(\Omega), j=0,1, \cdots\left[\frac{p-1}{2}\right]\right\}
$$

and we admit the notation that

$$
(-\Delta)^{\frac{p}{2}} u=\left\{\begin{array}{l}
\nabla(-\Delta)^{k-1} u, \quad(p=2 k-1) \\
(-\Delta)^{k} u, \quad(p=2 k)
\end{array}\right.
$$

for $k \in \mathbb{N}$. Then (1.1) is the Euler-Lagrange equation of $I_{\rho}$.
In the following, let $\alpha_{0}(p)$ denote the best constant for the Adams version Trudinger-Moser inequality [1]: there exists $C(\Omega)<+\infty$ such that for any $\alpha \leq \alpha_{0}(p)$ and $u \in C_{0}^{\infty}(\Omega)$ with

$$
\left\|(-\Delta)^{\frac{p}{2}} u\right\|_{L^{2}(\Omega)} \leq 1,
$$

there holds

$$
\int_{\Omega} e^{\alpha u^{2}} d x \leq C(\Omega)
$$

The same holds for $u \in X$ by standard density argument. It is known that $\alpha_{0}(1)=4 \pi, \alpha_{0}(2)=32 \pi^{2}$, and generally, $\alpha_{0}(p)=\frac{2 p}{\sigma_{2 p}}(2 \pi)^{2 p}=$ $2^{2 p} \pi^{p} p$ !, where $\sigma_{N}=\frac{2 \pi^{N / 2}}{\Gamma(N / 2)}$ denotes the volume of the unit sphere in
$\mathbb{R}^{N}$. Also $G=G(x, y)$ will denote the Green function of $(-\Delta)^{p}$ under the Navier boundary condition:

$$
\left\{\begin{array}{l}
(-\Delta)^{p} G(\cdot, y)=\delta_{y} \quad \text { in } \Omega \subset \mathbb{R}^{2 p}, \\
G(\cdot, y)=(-\Delta)^{j} G(\cdot, y)=0 \quad \text { on } \partial \Omega, \quad(j=1, \cdots p-1)
\end{array}\right.
$$

We decompose $G$ as $G(x, y)=\Gamma(x, y)-H(x, y)$, where $\Gamma(x, y)$ is the fundamental solution of $(-\Delta)^{p}$ on $\mathbb{R}^{2 p}$, defined as

$$
\Gamma(x, y)=C_{p} \log \frac{1}{|x-y|}, \quad C_{p}=\frac{1}{\left\{2^{p-1}(p-1)!\right\}^{2} \sigma_{2 p}}
$$

and $H=H(x, y) \in C^{\infty}(\Omega \times \Omega)$ is called the regular part of the Green function. Finally, let $R(y)=H(y, y)$ denote the Robin function of the Green function of $(-\Delta)^{p}$ with the Navier boundary condition.

On the asymptotic behavior of blowing-up solutions to (1.1), C-S. Lin and J-C. Wei proved, among others, the following result; see [13], [11], [12].

Proposition 1.1. Assume $V \in C^{2, \beta}(\Omega), \inf _{\Omega} V>0$. Let $u_{\rho_{n}}$ be a solution sequence to (1.1) with $\rho=\rho_{n}>0$ such that $\left\|u_{\rho_{n}}\right\|_{L^{\infty}(\Omega)} \rightarrow \infty$ while $\rho_{n}=O(1)$ as $n \rightarrow \infty$. Then there exists a subsequence (again denoted by $\rho_{n}$ ) and m-points set $\mathcal{S}=\left\{a_{1}, \cdots, a_{m}\right\} \subset \Omega$ (blow up set) such that

$$
\begin{aligned}
& \rho_{n} \rightarrow 2 \alpha_{0}(p) m, \quad \text { (mass quantization) } \\
& u_{\rho_{n}} \rightarrow 2 \alpha_{0}(p) \sum_{j=1}^{m} G\left(\cdot, a_{j}\right) \quad \text { in } C_{l o c}^{2 p}(\bar{\Omega} \backslash \mathcal{S}), \\
& \rho_{n} \frac{V(x) e^{u_{\rho_{n}}}}{\int_{\Omega} V(x) e^{u_{\rho_{n}}} d x} \rightharpoonup 2 \alpha_{0}(p) \sum_{i=1}^{m} \delta_{a_{i}}
\end{aligned}
$$

in the sense of measures. Finally, each blow up point $a_{i} \in \mathcal{S}$ must satisfy

$$
\begin{equation*}
\frac{1}{2} \nabla R\left(a_{i}\right)-\sum_{j=1, j \neq i}^{m} \nabla_{x} G\left(a_{i}, a_{j}\right)-\frac{1}{2 \alpha_{0}(p)} \nabla \log V\left(a_{i}\right)=\overrightarrow{0}, \tag{1.2}
\end{equation*}
$$

for $i=1, \cdots, m$. (Characterization of blow up points)
The main difficult point in the proof is to show that the blow up set $\mathcal{S}$ consists of interior points of $\Omega$. In [11], [12], the authors used the local version of the method of moving planes to overcome the difficulty. After showing that $\mathcal{S} \subset \Omega$, the rest of claims follow by the argument in [13].

As for the actual existence of multi-bubble solutions to (1.1), which exhibits the asymptotic behavior described in Proposition 1.1 with $m \geq$ 2 , some affirmative results are known by recent papers [2] [6] when $p=2$.

Proposition 1.2. Let $p=2$ and $m \geq 2$ be an integer. Set $\Omega^{m}=\Omega \times$ $\cdots \times \Omega$ ( $m$ times) and $\Delta=\left\{\left(\xi_{1}, \cdots, \xi_{m}\right) \in \Omega^{m} \mid \xi_{i}=\xi_{j}\right.$ for some $\left.i \neq j\right\}$. Define the Hamiltonian function

$$
\mathcal{F}\left(\xi_{1}, \cdots, \xi_{m}\right)=\sum_{i=1}^{m}\left(R\left(\xi_{i}\right)-\frac{1}{32 \pi^{2}} \log V\left(\xi_{i}\right)\right)-\sum_{\substack{i \neq j \\ 1 \leq i, j \leq m}} G\left(\xi_{i}, \xi_{j}\right)
$$

on $\Omega^{m} \backslash \Delta$. If $\mathcal{F}$ has a nondegenerate critical point (Baraket-Dammak-Ouni-Pacard [2], $V \equiv 1$ case), or, a "minimax value in an appropriate subset" (Clapp-Munõz-Musso [6]), that is, if $\left(a_{1}, \cdots, a_{m}\right) \in \Omega^{m} \backslash \Delta$ satisfies

$$
\frac{1}{2} \nabla R\left(a_{i}\right)-\sum_{j=1, j \neq i}^{m} \nabla_{x} G\left(a_{i}, a_{j}\right)-\frac{1}{64 \pi^{2}} \nabla \log V\left(a_{i}\right)=\overrightarrow{0}
$$

for $i=1,2, \cdots, m$ and some additional conditions, then there exists a solution sequence $\left\{u_{\rho}\right\}$ which blows up exactly on $\mathcal{S}=\left\{a_{1}, \cdots, a_{m}\right\}$.

For the precise meaning that $\mathcal{F}$ has a "minimax value in an appropriate subset", we refer to [6]. By this proposition, we know that if $\Omega$ has the cohomology group $H^{d}(\Omega) \neq 0$ for some $d \in \mathbb{N}$, or, if $\Omega$ is an $m$-dumbbell shaped domain (roughly, a simply-connected domain made by $m$ balls those connected to each other by thin tubes), then there exist $m$-points blowing up solutions for any $m \geq 2$ [6].

In this paper, on the contrary, we prove the nonexistence of multibubble solutions to (1.1) on convex domains, under an additional assumption on the coefficient function $V$.
Theorem 1.3. Assume $\Omega \subset \mathbb{R}^{2 p}$ be a bounded convex domain. Let $\left\{u_{\rho_{n}}\right\}$ be a solution sequence to (1.1) satisfying $\left\|u_{\rho_{n}}\right\|_{L^{\infty}(\Omega)}$ is not bounded while $\rho_{n}>0$ is bounded as $n \rightarrow \infty$. Assume $\inf _{\Omega} V>0$ and $R-$ $\frac{1}{\alpha_{0}(p)} \log V$ is a strictly convex function on $\Omega$. Then there exists $a \in \Omega$ such that, for the full sequence, we have

$$
\begin{aligned}
& \rho_{n} \rightarrow 2 \alpha_{0}(p), \\
& u_{\rho_{n}} \rightarrow 2 \alpha_{0}(p) G(\cdot, a) \quad \text { in } C_{l o c}^{2 p}(\bar{\Omega} \backslash\{a\}), \\
& \rho_{n} \frac{V(x) e^{u_{\rho_{n}}}}{\int_{\Omega} V(x) e^{u_{\rho_{n}}} d x} \rightharpoonup 2 \alpha_{0}(p) \delta_{a} \quad \text { in the sense of measures }
\end{aligned}
$$

$$
\text { as } n \rightarrow \infty \text {. }
$$

In this theorem, we can claim also that $a \in \Omega$ is the unique minimum point of the strictly convex function $R-\frac{1}{\alpha_{0}(p)} \log V$.

We remark here that, for the 2nd order case, the Robin function of $-\Delta$ with the Dirichlet boundary condition on a bounded convex domain $\Omega$ in $\mathbb{R}^{N}$ is strictly convex on $\Omega$. This fact was first proved by Caffarelli and Friedman [4] when $N=2$, and later extended to $N \geq 3$ by Cardaliaguet and Tahraoui [5]. By using this fact, Grossi and Takahashi [9] proved that blowing-up solutions with multiple blow up points do not exist on convex domains for various semilinear problems with blowing-up or concentration phenomena. It is open whether the same convexity holds true or not for the Robin function of $(-\Delta)^{p}$ under the Navier boundary condition when $p \geq 2$. Thus at this stage, we cannot drop the assumption on $V$ and we do not know whether the same result as Theorem 1.3 is true when $V$ is a constant.

This paper is organized as follows. In $\S 2$, we prove a lemma which is crucial to our argument. In this lemma, we do not need the assumption of the convexity of $\Omega$. In $\S 3$, we prove Theorem 1.3 by using the key lemma in $\S 2$ and the characterization of blow up points (1.2).

## 2. New Pohozaev identity for the Green function.

In this section, we prove an integral identity for the Green function of $(-\Delta)^{p}$ with the Navier boundary condition, which is a key for the proof of Theorem 1.3. Corresponding identity when $p=1$ was former proved in [9].

Proposition 2.1. Let $\Omega \subset \mathbb{R}^{N}(N \geq 2 p)$ be a smooth bounded domain. For any $P \in \mathbb{R}^{N}$ and $a, b \in \Omega, a \neq b$, it holds

$$
\begin{aligned}
& \sum_{k=1}^{p} \int_{\partial \Omega}(x-P) \cdot \nu(x)\left(\frac{\partial(-\Delta)^{p-k} G_{a}}{\partial \nu_{x}}\right)\left(\frac{\partial(-\Delta)^{k-1} G_{b}}{\partial \nu_{x}}\right) d s_{x} \\
& =(2 p-N) G(a, b)+(P-a) \cdot \nabla_{x} G(a, b)+(P-b) \cdot \nabla_{x} G(b, a),
\end{aligned}
$$

where $G_{a}(x)=G(x, a), G_{b}(x)=G(x, b)$ and $\nu(x)$ is the unit outer normal at $x \in \partial \Omega$.

Proof. We follow the argument used in [9], which originates from [3]. In order to introduce the idea clearly, first we show a formal computation. Let us denote $G_{a}(x)=G(x, a), G_{b}(x)=G(x, b)$ and define $w(x)=(x-P) \cdot \nabla G_{a}(x)$. Since $\Delta^{j}((x-P) \cdot \nabla)=2 j \Delta^{j}+$
$\left((x-P) \cdot \nabla \Delta^{j}\right)$ for $j \in\{0\} \cup \mathbb{N}$, we have

$$
\begin{cases}(-\Delta)^{p} w(x) & =(x-P) \cdot \nabla \delta_{a}(x)+2 p \delta_{a}(x) \\ (-\Delta)^{p} G_{b}(x) & =\delta_{b}(x)\end{cases}
$$

where $\delta_{a}, \delta_{b}$ are the Dirac delta functions supported on $a, b$ respectively. Multiplying $G_{b}(x), w(x)$ respectively to the above equations, and subtracting, we obtain

$$
\begin{align*}
& \int_{\Omega}\left((-\Delta)^{p} w(x)\right) G_{b}(x)-\left((-\Delta)^{p} G_{b}(x)\right) w(x) d x \\
& =\int_{\Omega}\left\{(x-P) \cdot \nabla \delta_{a}(x) G_{b}(x)+2 p \delta_{a}(x) G_{b}(x)-\delta_{b}(x) w(x)\right\} d x . \tag{2.1}
\end{align*}
$$

By an iterated use of Green's second formula, we see

$$
\text { LHS of } \begin{aligned}
(2.1) & =(-1)^{p} \sum_{k=1}^{p} \int_{\partial \Omega}\left(\frac{\partial \Delta^{p-k} w}{\partial \nu} \Delta^{k-1} G_{b}-\frac{\partial \Delta^{k-1} G_{b}}{\partial \nu} \Delta^{p-k} w\right) d s_{x} \\
& =(-1)^{p+1} \sum_{k=1}^{p} \int_{\partial \Omega}\left((x-P) \cdot \nabla \Delta^{p-k} G_{a}\right)\left(\frac{\partial \Delta^{k-1} G_{b}}{\partial \nu}\right) d s_{x} \\
& =\sum_{k=1}^{p} \int_{\partial \Omega}(x-P) \cdot \nu(x)\left(\frac{\partial(-\Delta)^{p-k} G_{a}}{\partial \nu_{x}}\right)\left(\frac{\partial(-\Delta)^{k-1} G_{b}}{\partial \nu_{x}}\right) d s_{x},
\end{aligned}
$$

here we have used $\Delta^{k-1} G_{b}=0$ and $\Delta^{p-k} w=(x-P) \cdot \nabla \Delta^{p-k} G_{a}$ on $\partial \Omega$.

On the other hand,

$$
\begin{aligned}
\operatorname{RHS} \text { of }(2.1) & =2 p G_{b}(a)-w(b)+\int_{\Omega}(x-P) \cdot \nabla \delta_{a}(x) G_{b}(x) d x \\
& =2 p G_{b}(a)-w(b)+\sum_{i=1}^{N} \int_{\Omega}\left(x_{i}-P_{i}\right) \frac{\partial \delta_{a}}{\partial x_{i}} G_{b}(x) d x \\
& =2 p G_{b}(a)-w(b)-\sum_{i=1}^{N} \int_{\Omega} \frac{\partial}{\partial x_{i}}\left\{\left(x_{i}-P_{i}\right) G_{b}(x)\right\} \delta_{a}(x) d x \\
& =2 p G_{b}(a)-w(b)-\left.\sum_{i=1}^{N} \frac{\partial}{\partial x_{i}}\left\{\left(x_{i}-P_{i}\right) G_{b}(x)\right\}\right|_{x=a} \\
& =(2 p-N) G(a, b)+(P-a) \cdot \nabla_{x} G(a, b)+(P-b) \cdot \nabla_{x} G(b, a) .
\end{aligned}
$$

Thus we obtain the conclusion.
To make this argument rigorously, we use standard approximations. Define $\delta_{a, \rho}(x)=\frac{1}{\left|B_{\rho}\right|} \chi_{B_{\rho}(a)}(x)$ where $\chi_{B_{\rho}(a)}$ is the characteristic function of the ball $B_{\rho}(a)$ with radius $\rho>0$ and center $a \in \Omega$. Denote $\delta_{a, \rho}^{\varepsilon}(x)=$
$j_{\varepsilon} * \delta_{a, \rho}(x)$ where $j(x) \geq 0, \operatorname{supp} j \subset B_{1}(0), \int_{\mathbb{R}^{N}} j(x) d x=1$ and $j_{\varepsilon}(x)=$ $\varepsilon^{-N} j\left(\frac{x-a}{\varepsilon}\right)$. For a point $a \in \Omega$ and for $\rho>0$ and $\varepsilon>0$ sufficiently small such that $B_{\rho+\varepsilon}(a) \subset \Omega, \delta_{a, \rho}^{\varepsilon}$ is well-defined and a smooth function on $\Omega$. Let $u_{a, \rho}^{\varepsilon}$ denote the unique solution of the problem

$$
\begin{cases}(-\Delta)^{p} u_{a, \rho}^{\varepsilon}=\delta_{a, \rho}^{\varepsilon} & \text { in } \Omega \\ (-\Delta)^{j} u_{a, \rho}^{\varepsilon}=0 & \text { on } \partial \Omega,(j=0,1, \cdots, p-1)\end{cases}
$$

Define $\delta_{b, \rho}^{\varepsilon}, u_{b, \rho}^{\varepsilon}$ in the same way. Since $\delta_{a, \rho}^{\varepsilon} \rightarrow \delta_{a, \rho}$ as $\varepsilon \rightarrow 0$ in $L^{q}(\Omega)$ for any $1 \leq q<\infty, u_{a, \rho}^{\varepsilon} \rightarrow u_{a, \rho}$ in $W^{2 p, q}(\Omega)$ as $\varepsilon \rightarrow 0$, where $u_{a, \rho}$ is the unique solution of

$$
\left\{\begin{array}{l}
(-\Delta)^{p} u_{a, \rho}=\delta_{a, \rho} \quad \text { in } \Omega \\
(-\Delta)^{j} u_{a, \rho}=0 \quad \text { on } \partial \Omega,(j=0,1, \cdots, p-1)
\end{array}\right.
$$

Since $\delta_{a, \rho} \rightarrow \delta_{a}$ as $\rho \rightarrow 0$, we have

$$
\lim _{\rho \rightarrow 0} \lim _{\varepsilon \rightarrow 0} u_{a, \rho}^{\varepsilon}=G(\cdot, a)
$$

in $C_{l o c}^{k}(\bar{\Omega} \backslash\{a\})$ for any $k \in \mathbb{N}$, and the same holds for $u_{b, \rho}^{\varepsilon}$.
Define $w(x)=(x-P) \cdot \nabla u_{a, \rho}^{\varepsilon}(x)$. Simple calculation shows that $w$ satisfies

$$
\begin{equation*}
(-\Delta)^{p} w=(x-P) \cdot \nabla_{x} \delta_{a, \rho}^{\varepsilon}+2 p \delta_{a, \rho}^{\varepsilon} . \tag{2.2}
\end{equation*}
$$

Multiply $u_{b, \rho}^{\varepsilon}$ to (2.2), $w$ to the equation $-\Delta u_{b, \rho}^{\varepsilon}=\delta_{b, \rho}^{\varepsilon}$, subtracting, and integrating on $\Omega$, we have

$$
\begin{align*}
& \int_{\Omega}\left((-\Delta)^{p} u_{b, \rho}^{\varepsilon}\right) w-\left((-\Delta)^{p} w\right) u_{b, \rho}^{\varepsilon} d x \\
& =\int_{\Omega}\left[2 p \delta_{a, \rho}^{\varepsilon}(x) u_{b, \rho}^{\varepsilon}(x)+(x-P) \cdot \nabla_{x} \delta_{a, \rho}^{\varepsilon}(x) u_{b, \rho}^{\varepsilon}(x)-\delta_{b, \rho}^{\varepsilon}(x) w(x)\right] d x \tag{2.3}
\end{align*}
$$

The LHS of (2.3) is

$$
\begin{aligned}
& (-1)^{p} \sum_{k=1}^{p} \int_{\partial \Omega}\left(\frac{\partial \Delta^{p-k} w}{\partial \nu} \Delta^{k-1} u_{b, \rho}^{\varepsilon}-\frac{\partial \Delta^{k-1} u_{b, \rho}^{\varepsilon}}{\partial \nu} \Delta^{p-k} w\right) d s_{x} \\
& =(-1)^{p+1} \sum_{k=1}^{p} \int_{\partial \Omega}\left((x-P) \cdot \nabla \Delta^{p-k} u_{a, \rho}^{\varepsilon}\right)\left(\frac{\partial \Delta^{k-1} u_{b, \rho}^{\varepsilon}}{\partial \nu}\right) d s_{x} \\
& =\sum_{k=1}^{p} \int_{\partial \Omega}(x-P) \cdot \nu(x)\left(\frac{\partial(-\Delta)^{p-k} u_{a, \rho}^{\varepsilon}}{\partial \nu_{x}}\right)\left(\frac{\partial(-\Delta)^{k-1} u_{b, \rho}^{\varepsilon}}{\partial \nu_{x}}\right) d s_{x} \\
& \rightarrow \sum_{k=1}^{p} \int_{\partial \Omega}(x-P) \cdot \nu(x)\left(\frac{\partial(-\Delta)^{p-k} G_{a}}{\partial \nu_{x}}\right)\left(\frac{\partial(-\Delta)^{k-1} G_{b}}{\partial \nu_{x}}\right) d s_{x}
\end{aligned}
$$

as $\varepsilon \rightarrow 0$ and then $\rho \rightarrow 0$.
The RHS of (2.3) is

$$
2 p \int_{\Omega} \delta_{a, \rho}^{\varepsilon}(x) u_{b, \rho}^{\varepsilon}(x) d x+\int_{\Omega} \sum_{i=1}^{N}\left(x_{i}-P_{i}\right)\left(\frac{\partial \delta_{a, \rho}^{\varepsilon}}{\partial x_{i}}(x)\right) u_{b, \rho}^{\varepsilon}(x) d x-\int_{\Omega} \delta_{b, \rho}^{\varepsilon}(x) w(x) d x .
$$

Now, integrating by parts, we have

$$
\begin{aligned}
& \sum_{i=1}^{N} \int_{\Omega}\left(x_{i}-P_{i}\right)\left(\frac{\partial \delta_{a, \rho}^{\varepsilon}(x)}{\partial x_{i}}\right) u_{b, \rho}^{\varepsilon}(x) d x \\
& =-\sum_{i=1}^{N} \int_{\Omega} \frac{\partial}{\partial x_{i}}\left\{\left(x_{i}-P_{i}\right) u_{b, \rho}^{\varepsilon}(x)\right\} \delta_{a, \rho}^{\varepsilon}(x) d x \\
& =-N \int_{\Omega} \delta_{a, \rho}^{\varepsilon}(x) u_{b, \rho}^{\varepsilon}(x) d x-\int_{\Omega}(x-P) \cdot \nabla u_{b, \rho}^{\varepsilon}(x) \delta_{a, \rho}^{\varepsilon}(x) d x
\end{aligned}
$$

thus

$$
\begin{aligned}
& \text { RHS of }(2.3)=(2 p-N) \int_{\Omega} \delta_{a, \rho}^{\varepsilon}(x) u_{b, \rho}^{\varepsilon}(x) d x \\
& -\int_{\Omega}(x-P) \cdot \nabla u_{b, \rho}^{\varepsilon}(x) \delta_{a, \rho}^{\varepsilon}(x) d x-\int_{\Omega}(x-P) \cdot \nabla u_{a, \rho}^{\varepsilon}(x) \delta_{b, \rho}^{\varepsilon}(x) d x \\
& \rightarrow(2 p-N) G(a, b) \\
& -\int_{\Omega}(x-P) \cdot \nabla_{x} G(x, b) \delta_{a}(x) d x-\int_{\Omega}(x-P) \cdot \nabla_{x} G(x, a)(x) \delta_{b}(x) d x \\
& =(2 p-N) G(a, b)+(P-a) \cdot \nabla_{x} G(a, b)+(P-b) \cdot \nabla_{x} G(b, a)
\end{aligned}
$$

as $\varepsilon \rightarrow 0$ and then $\rho \rightarrow 0$. This proves Lemma 2.1.

## 3. Proof of Theorem 1.3.

In this section, we prove Theorem 1.3 along the same line in [9].

## Step 1.

We argue by contradiction and assume that there exists a $m$-points set $\mathcal{S}=\left\{a_{1}, \cdots, a_{m}\right\} \subset \Omega(m \geq 2)$ satisfying (1.2). Set $K(x)=$ $\frac{1}{2} R(x)-\frac{1}{2 \alpha_{0}(p)} \log V(x)$.
$P \in \Omega$ is chosen later. Multiplying $P-a_{i}$ to (1.2) and summing up, we have

$$
\begin{align*}
& \sum_{i=1}^{m}\left(P-a_{i}\right) \cdot \nabla K\left(a_{i}\right)=\sum_{i=1}^{m} \sum_{j=1, j \neq i}^{m}\left(P-a_{i}\right) \cdot \nabla_{x} G\left(a_{i}, a_{j}\right)  \tag{3.1}\\
& =\sum_{1 \leq j<k \leq m}\left\{\left(P-a_{j}\right) \cdot \nabla_{x} G\left(a_{j}, a_{k}\right)+\left(P-a_{k}\right) \cdot \nabla_{x} G\left(a_{k}, a_{j}\right)\right\}
\end{align*}
$$

## Step 2.

By proposition 2.1, we obtain

$$
\begin{aligned}
& \left(P-a_{j}\right) \cdot \nabla_{x} G\left(a_{j}, a_{k}\right)+\left(P-a_{k}\right) \cdot \nabla_{x} G\left(a_{k}, a_{j}\right) \\
= & \sum_{l=1}^{p} \int_{\partial \Omega}(x-P) \cdot \nu(x)\left(\frac{\partial(-\Delta)^{p-l} G\left(x, a_{j}\right)}{\partial \nu_{x}}\right)\left(\frac{\partial(-\Delta)^{l-1} G\left(x, a_{k}\right)}{\partial \nu_{x}}\right) d s_{x} .
\end{aligned}
$$

By the convexity of $\Omega$, we have $(x-P) \cdot \nu(x)>0$ on $\partial \Omega$. Also by Hopf lemma, we obtain $\frac{\partial(-\Delta)^{p-l} G\left(x, a_{j}\right)}{\partial \nu_{x}}<0, \frac{\partial(-\Delta)^{l-1} G\left(x, a_{k}\right)}{\partial \nu_{x}}<0$ for $x \in \partial \Omega$. Thus we see the right hand side of (3.1) is positive, and get

$$
\begin{equation*}
\sum_{i=1}^{m}\left(a_{i}-P\right) \cdot \nabla K\left(a_{i}\right)<0 \tag{3.2}
\end{equation*}
$$

## Step 3.

By assumption, $K(x)=\frac{1}{2} R(x)-\frac{1}{2 \alpha_{0}(p)} \log V(x)$ is strictly convex. Thus, all level sets of $K$ is strictly star-shaped with respect to its unique minimum point $P \in \Omega$. Choose $P$ as the minimum point. Then

$$
\begin{equation*}
(a-P) \cdot \nabla K(a) \geq 0, \quad \forall a \in \Omega \backslash\{P\} \tag{3.3}
\end{equation*}
$$

In particular,

$$
\sum_{i=1}^{m}\left(a_{i}-P\right) \cdot \nabla K\left(a_{i}\right) \geq 0
$$

Now, (3.2) and (3.3) leads to an obvious contradiction. Thus we have $m=1$ and the rest of proof is easily done by Proposition 1.1.

Acknowledgement. This work was partly supported by JSPS Grant-in-Aid for Scientific Research (KAKENHI) (B), No. 23340038.

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