

On the moduli space of left-invariant metrics on a Lie group

Hiroshi Tamaru (Hiroshima University)

**Submanifold Theory in Symmetric Spaces and Lie Theory in
Finite and Infinite Dimensions**

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1 Introduction

1.1 Abstract

Theme:

- G : a given Lie group.
- Examine whether G admits a “distinguished” left-inv. metric.
(e.g., Einstein, Ricci soliton)

Successful case:

- Well-studied for 3-dim. unimodular Lie groups.
- By Milnor (1976), using so-called “Milnor frame”.

Our study:

- The “moduli space” of left-invariant metric on a Lie group.
- This generalizes Milnor frame to “any” Lie groups.

1.2 Contents

This talk is organized as follows:

- **§2: Preliminaries: Milnor frame**
- **§3: The moduli space of left-invariant metrics**
- **§4: Milnor-type theorems**
- **§5: A pseudo-Riemannian version**
- **§6: Summary and Problems**

2 Preliminaries: Milnor frame

2.1 Milnor frame (1/3)

Thm (Milnor, 1976):

- \mathfrak{g} : 3-dim. unimodular
- \langle , \rangle : any inner product on \mathfrak{g}
 - $\Rightarrow \exists \{x_1, x_2, x_3\} : \text{o.n.b. wrt } \langle , \rangle, \exists \lambda_1, \lambda_2, \lambda_3 \in \mathbb{R} :$
 $[x_1, x_2] = \lambda_3 x_3, [x_2, x_3] = \lambda_1 x_1, [x_3, x_1] = \lambda_2 x_2.$

Remark:

- For each \mathfrak{g} , possible values of $\lambda_1, \lambda_2, \lambda_3$ are determined.
- One can examine all inner products on \mathfrak{g} .

2.2 Milnor frame (2/3) - application

Example:

- \langle, \rangle : any inner product on $\mathfrak{g} := \mathfrak{sl}(2, \mathbb{R})$
 - \Rightarrow ◦ $\exists \{x_1, x_2, x_3\}$: o.n.b. wrt \langle, \rangle , $\exists \lambda_1 > 0, \lambda_2 > 0, \lambda_3 < 0$:
 $[x_1, x_2] = \lambda_3 x_3, [x_2, x_3] = \lambda_1 x_1, [x_3, x_1] = \lambda_2 x_2.$
 - The eigenvalues of $\text{Ric}_{\langle, \rangle}$ satisfy either $(+, -, -)$ or $(0, 0, -)$

Cor.:

- $\text{SL}(2, \mathbb{R})$ does not admit left-invariant Einstein metrics.

Comment:

- Thanks to Milnor's theorem,
curvature properties are completely understood
for 3-dim. unimodular Lie groups.

2.3 Milnor frame (3/3) - comments

Recall:

- $\forall \langle, \rangle$ on \mathfrak{g} , $\exists \{x_1, x_2, x_3\} : \text{o.n.b.}, \exists \lambda_1, \lambda_2, \lambda_3 : \dots$

Comment:

- Milnor's thm is quite useful.
- But, the proof strongly depends on $\dim = 3$.

Another view:

- Milnor's thm expresses

$$\tilde{\mathfrak{M}} := \{ \langle, \rangle : \text{inner products on } \mathfrak{g} \}.$$

- $\tilde{\mathfrak{M}} \cong \text{GL}_3(\mathbb{R})/\text{O}(3) : \dim = 6$.

- $(\lambda_1, \lambda_2, \lambda_3)$ represents

$$\text{Aut}(\mathfrak{g}) \backslash \tilde{\mathfrak{M}}, \text{ the "moduli space"}.$$

3 The moduli space of left-invariant metrics

3.1 The moduli space (1/6) - the space of left-inv. metrics

Fact:

- G : n -dim. Lie group with Lie algebra \mathfrak{g}
 - $\Rightarrow \tilde{\mathfrak{M}} := \{g : \text{a left-inv. Riemannian metric on } G\}$
 - $\cong \{\langle \cdot, \cdot \rangle : \text{an inner product on } \mathfrak{g}\}$
 - $\cong \text{GL}_n(\mathbb{R})/\text{O}(n).$

Note that:

- We identify $\mathfrak{g} \cong \mathbb{R}^n$, $\text{GL}(\mathfrak{g}) \cong \text{GL}_n(\mathbb{R})$.
- $\text{GL}_n(\mathbb{R})$ acts on $\tilde{\mathfrak{M}}$ by $g.\langle \cdot, \cdot \rangle := \langle g^{-1}\cdot, g^{-1}\cdot \rangle$.

3.2 The moduli space (2/6) - def

Def.:

- $\mathbb{R}^\times \text{Aut}(\mathfrak{g}) := \{c\varphi \in \text{GL}_n(\mathbb{R}) \mid c \in \mathbb{R}^\times, \varphi \in \text{Aut}(\mathfrak{g})\}$.
- $\mathfrak{M} := \mathbb{R}^\times \text{Aut}(\mathfrak{g}) \backslash \tilde{\mathfrak{M}}$ (the orbit space)

is called the moduli space of left-invariant metrics.

Remark:

- $\exists \varphi \in \mathbb{R}^\times \text{Aut}(\mathfrak{g}) : \varphi \cdot \langle, \rangle_1 = \langle, \rangle_2$
 - \Rightarrow the corresponding left-invariant metrics are isometric up to scaling
 - \Rightarrow all curvature properties are preserved.
- By considering \mathfrak{M} , one can study all left-invariant metrics.

3.3 The moduli space (3/6) - trivial cases

Thm. (Lauret, 2003):

- A Lie algebra \mathfrak{g} satisfies $\mathfrak{M} = \{\text{pt}\}$
 - \Leftrightarrow (1) \mathbb{R}^n : abelian,
 - (2) $\mathfrak{g}_{\mathbb{R}H^n} := \text{span}\{e_1, \dots, e_n\}$ with $[e_1, e_j] = e_j$ ($j \geq 2$),
 - (3) $\mathfrak{h}_3 \oplus \mathbb{R}^{n-3} := \text{span}\{e_1, \dots, e_n\}$ with $[e_1, e_2] = e_3$.

Comment:

- Milnor (1976): $\forall \langle, \rangle$ on $\mathfrak{g}_{\mathbb{R}H^n}$ has a constant curvature $c < 0$.
- This can be checked easily from $\mathfrak{M} = \{\text{pt}\}$.

Remark:

- Lauret's proof uses a degeneration of Lie brackets.
- Kodama-Takahara-T. (2011) proved (\Leftrightarrow) by checking $\mathbb{R}^\times \text{Aut}(\mathfrak{g}) \curvearrowright \tilde{\mathfrak{M}}$ is transitive.

3.4 The moduli space (4/6) - an expression

Prop.:

- $\mathfrak{B}\mathfrak{M} = \mathbb{R}^\times \text{Aut}(\mathfrak{g}) \backslash \widetilde{\mathfrak{M}} \cong \mathbb{R}^\times \text{Aut}(\mathfrak{g}) \backslash \text{GL}_n(\mathbb{R}) / \text{O}(n).$

Remark:

- In order to express $\mathfrak{B}\mathfrak{M}$, one needs to express $\mathbb{R}^\times \text{Aut}(\mathfrak{g})$.
- In general, it is not easy.
- $\mathbb{R} \oplus \text{Der}(\mathfrak{g}) = \text{Lie}(\mathbb{R}^\times \text{Aut}(\mathfrak{g}))$, relatively easier to determine.
- If one knows $\mathbb{R}^\times \text{Aut}(\mathfrak{g})$, then the remainings are linear algebra...

Comment:

- In general, $\mathfrak{B}\mathfrak{M}$ is a complicated space.
- If $\mathbb{R}^\times \text{Aut}(\mathfrak{g}) \curvearrowright \widetilde{\mathfrak{M}}$ is nice (e.g., low cohomogeneity, (hyper-)polar) then $\mathfrak{B}\mathfrak{M}$ is nice.

3.5 The moduli space (5/6) - a remark on orbit spaces

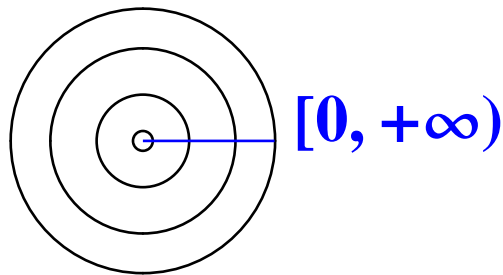
Recall:

- $\widetilde{\mathfrak{M}} = \mathrm{GL}_n(\mathbb{R})/\mathrm{O}(n)$: a noncompact symmetric space.

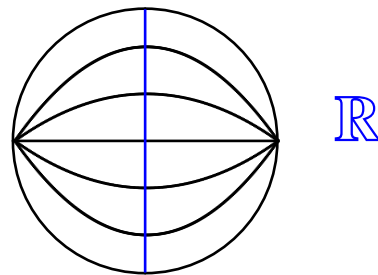
Thm. (Berndt-Brück 2001):

- M : a noncompact symmetric space
- $H \curvearrowright M$: cohomogeneity one (with H connected)
 $\Rightarrow H \backslash M \cong \mathbb{R}$ or $[0, +\infty)$.

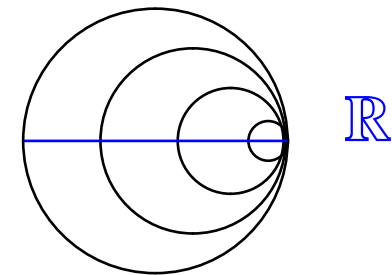
Example (cohomogeneity one actions on $\mathbb{R}H^2$):



$$\mathrm{SO}(2) \curvearrowright \mathbb{R}H^2$$



$$A \curvearrowright \mathbb{R}H^2$$



$$N \curvearrowright \mathbb{R}H^2$$

3.6 The moduli space (6/6) - an example

Example (Hashinaga-T.-Terada, preprint):

- $\mathfrak{g} = \text{span}\{e_1, e_2, e_3, e_4\}$ with $[e_1, e_2] = e_2$
- \langle, \rangle_0 : inner product s.t. the above basis is orthonormal

$$\Rightarrow \circ \mathbb{R} \oplus \text{Der}(\mathfrak{g}) = \left\{ \begin{array}{c|ccc} * & \mathbf{0} & \mathbf{0} & \mathbf{0} \\ \hline * & * & * & \mathbf{0} \\ * & * & * & \mathbf{0} \\ \hline * & \mathbf{0} & \mathbf{0} & * \end{array} \right\},$$

◦ $\mathbb{R}^\times \text{Aut}(\mathfrak{g}) \curvearrowright \tilde{\mathfrak{M}}$: cohomogeneity one.

◦ $\mathfrak{PM} = \{\mathbb{R}^\times \text{Aut}(\mathfrak{g}).(g_\lambda.\langle, \rangle_0) \mid g_\lambda \in \mathcal{U}\},$

$$\text{where } \mathcal{U} = \left\{ \begin{array}{c|ccc} \mathbf{1} & \mathbf{0} & \mathbf{0} & \mathbf{0} \\ \hline \mathbf{0} & \mathbf{1} & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{1} & \mathbf{0} \\ \hline \mathbf{0} & \lambda & \mathbf{0} & \mathbf{1} \end{array} \right\}, \lambda \geq 0 \cong [0, +\infty).$$

4 Milnor-type theorems

4.1 Milnor-type theorems (1/4) - a key theorem

Thm. (Hashinaga-T.-Terada, preprint):

- \mathfrak{g} : Lie algebra
- $\{e_1, \dots, e_n\}$: o.n.b. of \mathfrak{g} wrt \langle, \rangle_0
- $GL_n(\mathbb{R}) \supset \mathcal{U}$: a set of representatives of \mathfrak{PM}
(i.e., $\mathfrak{PM} = \{\mathbb{R}^\times \text{Aut}(\mathfrak{g}).(g.\langle, \rangle_0) \mid g \in \mathcal{U}\}$)
- \langle, \rangle : an arbitrary inner product
 $\Rightarrow \exists k > 0, \exists \varphi \in \text{Aut}(\mathfrak{g}), \exists g \in \mathcal{U}$:
 $\{\varphi g e_1, \dots, \varphi g e_n\}$ is orthonormal wrt $k\langle, \rangle$.

A sketch of Proof:

- By assumption, $\exists g \in \mathcal{U} : \langle, \rangle \in \mathbb{R}^\times \text{Aut}(\mathfrak{g}).(g.\langle, \rangle_0)$.
- By definition, $\exists c\varphi \in \mathbb{R}^\times \text{Aut}(\mathfrak{g}) : \langle, \rangle = (c\varphi g).\langle, \rangle_0$.

4.2 Milnor-type theorems (2/4) - a comment

Recall:

- $GL_n(\mathbb{R}) \supset \mathfrak{U}$: a set of representatives of \mathfrak{PM}
- \langle, \rangle : an arbitrary inner product
- $\Rightarrow \exists k > 0, \exists \varphi \in \text{Aut}(\mathfrak{g}), \exists g \in \mathfrak{U} :$
 $\{\varphi g e_1, \dots, \varphi g e_n\}$ is orthonormal wrt $k\langle, \rangle$.

Comment:

- By checking the bracket relations among $\{\varphi g e_1, \dots, \varphi g e_n\}$, one can get a Milnor-type theorem.
- Note: φ preserves a bracket product.

4.3 Milnor-type theorems (3/4) - an example

Example (Milnor-type theorem):

- $\mathfrak{g} = \text{span}\{e_1, e_2, e_3, e_4\}$ with $[e_1, e_2] = e_2$

(Recall: $\mathfrak{u} \cong [0, +\infty)$)

- \langle, \rangle : an arbitrary inner product

$\Rightarrow \exists k > 0, \exists \lambda \geq 0, \exists \{x_1, x_2, x_3, x_4\} : \text{o.n.b. of } \mathfrak{g} \text{ wrt } k\langle, \rangle$

s.t. $[x_1, x_2] = x_2 + \lambda x_4$.

Cor.:

- $\mathfrak{g} = \text{span}\{e_1, e_2, e_3, e_4\}$ with $[e_1, e_2] = e_2$

\Rightarrow ◦ eigenvalues of Ric satisfy either $(+, 0, -, -)$ or $(0, 0, -, -)$.

- \nexists left-invariant Einstein metric.

4.4 Milnor-type theorems (4/4) - a remark

Recall:

- \mathcal{U} : a set of representatives of \mathfrak{PM}
⇒ one can get a Milnor-type theorem.

Comment:

- One can get Milnor-type theorems for ANY Lie algebras.
- If one has a nice \mathcal{U}
(e.g., $\mathbb{R}^\times \text{Aut}(\mathfrak{g}) \curvearrowright \tilde{\mathfrak{M}}$: cohomogeneity one, (hyper-)polar,...)
⇒ one gets a useful Milnor-type theorem as above.
- If not (e.g., $\mathbb{R}^\times \text{Aut}(\mathfrak{g})$ is very small)
⇒ One can get a Milnor-type theorem, but it is not useful...

5 A pseudo-Riemannian version

5.1 A pseudo version (1/5) - the moduli space

Def:

- \mathfrak{g} : $(p + q)$ -dim. Lie algebra
- $\widetilde{\mathfrak{M}}_{(p,q)} := \{ \langle \cdot, \cdot \rangle : \text{an inner product on } \mathfrak{g} \text{ with signature } (p, q) \}$
 $\cong \text{GL}_{p+q}(\mathbb{R}) / \text{O}(p, q)$.
- $\mathfrak{M}_{(p,q)} := \mathbb{R}^\times \text{Aut}(\mathfrak{g}) \backslash \widetilde{\mathfrak{M}}_{p+q}$: the Moduli space.

Thm. (Kubo-Onda-Taketomi-T., in preparation):

- A set of representatives of $\mathfrak{M}_{(p,q)}$
 \Rightarrow a pseudo-Riemannian version Milnor-type theorem
(by the same procedure)

5.2 A pseudo version (2/5) - a known result

Thm. (Nomizu, 1979):

- $\mathfrak{g} := \mathfrak{g}_{\mathbb{R}H^n} = \text{span}\{e_1, \dots, e_n\}$ with $[e_1, e_j] = e_j$ ($j \geq 2$)
 $\Rightarrow \forall \langle, \rangle : \text{Lorentz, it has a constant curvature } c.$
(c can take any signature, $c > 0$, $c = 0$, $c < 0$)

Comment:

- **His proof is very direct.**
- **Using $\mathfrak{PM}_{(p,q)}$, we can generalize this, and simplify the proof.**

5.3 A pseudo version (3/5) - a moduli space

Prop. (KOTT):

- $\mathfrak{g} := \mathfrak{g}_{\mathbb{R}H^{p+q}}$

- $\Rightarrow \#\mathfrak{M}_{(p,q)} = 3$, given by $\mathfrak{U} = \{I_n + \lambda E_{1,n} \mid \lambda = 0, 1, 2\}$.

Remark:

- $\mathfrak{M}_{(p,q)} := \mathbb{R}^\times \text{Aut}(\mathfrak{g}) \backslash \tilde{\mathfrak{M}}_{p+q} \cong \text{O}(p, q) \backslash (\text{GL}_{p+q}(\mathbb{R}) / \mathbb{R}^\times \text{Aut}(\mathfrak{g}))$

- If $\mathfrak{g} := \mathfrak{g}_{\mathbb{R}H^n}$, then

$\mathbb{R}^\times \text{Aut}(\mathfrak{g})$ is parabolic so that $\text{GL}_{p+q}(\mathbb{R}) / \mathbb{R}^\times \text{Aut}(\mathfrak{g}) \cong \mathbb{R}P^{p+q-1}$.

- The above 3 orbits correspond to

$\{[v] \in \mathbb{R}P^{p+q-1}\}$ with v : timelike, lightlike, spacelike.

5.4 A pseudo version (4/5) - a Milnor-type theorem

Recall:

- $\mathfrak{g} := \mathfrak{g}_{\mathbb{R}H^{p+q}}$
 $\Rightarrow \#\mathfrak{PM}_{(p,q)} = 3$, given by $\mathfrak{U} = \{I_n + \lambda E_{1,n} \mid \lambda = 0, 1, 2\}$.

Prop. (Milnor-type theorem):

- $\mathfrak{g} := \mathfrak{g}_{\mathbb{R}H^n}$
- \langle, \rangle : an arbitrary inner product with signature (p, q)
 $\Rightarrow \exists k > 0, \exists \lambda \in \{0, 1, 2\}$,
 $\exists \{x_1, \dots, x_n\}$: pseudo-o.n.b. wrt $k\langle, \rangle$:
 $[x_1, x_j] = x_j, [x_1, x_n] = -\lambda x_1 + x_n, [x_j, x_n] = -\lambda x_j$
(for $j \geq 2$)

5.5 A pseudo version (5/5) - Our theorem

Thm. (KOTT):

- $\mathfrak{g} := \mathfrak{g}_{\mathbb{R}H^n}$

- $\Rightarrow \forall \langle, \rangle$: pseudo-Riemannian, it has a constant curvature c .

- (c can take any signature, $c > 0$, $c = 0$, $c < 0$)

Comment:

- To get more examples, we need to know:

- isometric actions on pseudo-Riemannian symmetric spaces...

- (the orbit spaces, cohomogeneity one, (hyper-)polar actions, ...)

6 Summary and Problems

6.1 Summary

Story:

- **The moduli space of left-invariant metrics**
(both Riemannian and pseudo-Riemannian settings)
 - ⇒ Milnor-type theorems
 - ⇒ one can examine ALL left-invariant metrics
- **This can be applied to the existence and nonexistence problem of distinguished (e.g., Einstein, Ricci soliton) metrics**

Point:

- **Actions on symmetric spaces play important roles.**

6.2 Problems

Problem 1:

- **A continuation of this study, i.e.,**
 - **Get more Milnor-type theorems,**
 - **Study isometric actions on symmetric spaces**
(both Riemannian and pseudo-Riemannian cases).

Problem 2:

- **Apply our method to other geometric structures, e.g.,**
 - **left-invariant complex structures,**
 - **left-invariant symplectic structures, ...**